

Special Techniques for Kernel-Based Reconstruction of Functions from Meshless Data

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Overview

1. Scope of Symmetric Meshless Collocation
2. Complexity Reduction
3. Preconditioning

Part I

Scope of Symmetric Meshless Collocation

Hypotheses

- Linear mixed problem

$$L_i u = f_i \quad \text{in } \Omega_i \subset \mathbb{R}^d, \quad i = 1, 2, \dots,$$

- Existence and uniqueness of solution u in RKHS \mathcal{U} with kernel Φ
- $L_i u$ and $L_i^x L_i^y \Phi(x, y)$ continuous on Ω_i

Result

Then the minimum norm solution by meshless symmetric collocation on dense subsets of Ω_i converges towards u .

Linear Problems

Given Problem

$$L_i u = f_i \quad \text{in } \Omega_i \subset \mathbb{R}^d, \quad i = 1, 2, \dots,$$

Discretize:

$$\begin{aligned} ((L_i u)(x_{ji})) &= f_i(x_{ji}) \quad x_{ji} \in \Omega_i \quad \text{for all } j \in I_i \\ (\delta_{x_{ji}} \circ L_i)(u) &= \delta_{x_{ji}} f_i \quad x_{ji} \in \Omega_i \quad \text{for all } j \in I_i \end{aligned}$$

Generally:

$$\lambda(u) = f_\lambda \in \mathbb{R} \quad \text{for all } \lambda \in \Lambda$$

Generalized Interpolation

Given $\Lambda \subset \mathcal{U}^*$, $f : \Lambda \rightarrow \mathbb{R}$

Find $u \in \mathcal{U}$ with

$$\lambda(u) = f(\lambda) \in \mathbb{R} \text{ for all } \lambda \in \Lambda$$

Minimum Norm Reconstruction

Given $\Lambda \subset \mathcal{U}^*$, $f : \Lambda \rightarrow \mathbb{R}$

Assume exact solution $u \in \mathcal{U}$ with

$$\lambda(u) = f(\lambda) \in \mathbb{R} \text{ for all } \lambda \in \Lambda$$

Reconstruction $\tilde{u} \in \mathcal{U}$ with

$$\lambda(\tilde{u}) = f(\lambda) \in \mathbb{R} \text{ for all } \lambda \in \Lambda$$

with minimal norm $\|\tilde{u}\|_{\mathcal{U}}$

Simplification: Hilbert Space

Closed subspaces

$$\mathcal{U}_\Lambda^\perp := \{u \in \mathcal{U} : \lambda(u) = 0 \text{ for all } \lambda \in \Lambda\}$$

$$\mathcal{U}_\Lambda := (\mathcal{U}_\Lambda^\perp)^\perp$$

Decompose solution $u = u_\Lambda + u_\Lambda^\perp \in \mathcal{U}_\Lambda + \mathcal{U}_\Lambda^\perp$

- Minimal norm solution is $\tilde{u} = u_\Lambda$
- Unique reconstruction iff $\mathcal{U}_\Lambda^\perp = \{0\}$

Problem: Construct u or $\tilde{u} = u_\Lambda$

Reproducing Kernel Hilbert Spaces

Space \mathcal{U} of functions

Dual space \mathcal{U}^* of functionals

Reproduction Property

$$\lambda(u) = (u, \lambda^x \Phi(x, \cdot))_{\mathcal{U}} \text{ for all } u \in \mathcal{U}, \text{ for all } \lambda \in \mathcal{U}^*$$

Minimum Norm Solution

Given $\Lambda_N = \{\lambda_1, \dots, \lambda_N\} \subset \Lambda \subset \mathcal{U}^*$, $f : \Lambda \rightarrow \mathbb{R}$

Find $\tilde{u}_N \in \mathcal{U}$ of minimum norm $\|\tilde{u}_N\|_{\mathcal{U}}$ with

$$\lambda_j(\tilde{u}_N) = f(\lambda_j) \in \mathbb{R} \text{ for all } \lambda_j \in \Lambda_N$$

Solution:

- $\tilde{u}_N = \sum_k c_k \lambda_k^x \Phi(x, \cdot)$
- $\lambda_j(\tilde{u}_N) = \sum_k c_k \lambda_k^x \lambda_j^y \Phi(x, y) = f(\lambda_j)$

Used incrementally for **Greedy Techniques**

Problem: Usually $|\Lambda| = \infty$

Convergence

Given $\Lambda_N = \{\lambda_1, \dots, \lambda_N\} \subset \mathcal{U}^*$ for $N \rightarrow \infty$

Sequence of minimum norm solutions $\tilde{u}_N \in \mathcal{U}$ is a Cauchy sequence, thus convergent.

Reason: $\|\tilde{u}_N\|_{\mathcal{U}}^2 \nearrow \|\tilde{u}\|_{\mathcal{U}}^2 \leq \|u\|_{\mathcal{U}}^2$ is a Cauchy sequence.

Construction works for $|\Lambda| = |\mathbb{N}|$.

Problem: Usually $|\Lambda| > |\mathbb{N}|$.

Density

Given $\Lambda_N \subset \Lambda \subset \mathcal{U}^*$, $|\Lambda_N| = |\mathbb{I}N|$.

Construct minimal norm solution \tilde{u}_N for Λ_N .

Problem: $\tilde{u}_N = \tilde{u}$?

$$\lambda(\tilde{u}_N - \tilde{u}) = 0 \text{ for all } \lambda \in \Lambda_N$$

Assumption: Λ_N dense in Λ , i.e.

$$\begin{aligned} \lambda_j(v) &= 0 \quad \text{for all } \lambda_j \in \Lambda_N \\ \Rightarrow \lambda(v) &= 0 \quad \text{for all } \lambda \in \Lambda \end{aligned}$$

Density and Continuity

Example:

$$(L_i(\tilde{u}_N - \tilde{u})) (x_{ji}) = 0 \text{ for all } x_{ji} \in \Omega_i$$

Goal:

$$L_i(\tilde{u}_N) = L_i(\tilde{u}) \text{ on } \Omega_i$$

if both continuous and $x_{ji} \in \Omega_i$ dense.

Final Result: Hypotheses

- Linear mixed problem

$$L_i u = f_i \quad \text{in } \Omega_i \subset \mathbb{R}^d, \quad i = 1, 2, \dots,$$

- Existence and uniqueness of solution u in RKHS \mathcal{U} with kernel Φ
- $L_i u$ and $L_i^x L_i^y \Phi(x, y)$ continuous on Ω_i

Result

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Part II

Complexity Reduction

Goal

Relaxing interpolation/collocation conditions yields a complexity reduction

Connection to

- machine learning
- support vector machines

Minimum Norm Reconstruction

Given $\Lambda \subset \mathcal{U}^*$, $f : \Lambda \rightarrow \mathbb{R}$

Reconstruction $\tilde{u} \in \mathcal{U}$ with

$$\lambda(\tilde{u}) = f(\lambda) \in \mathbb{R} \text{ for all } \lambda \in \Lambda$$

with minimal norm $\|\tilde{u}\|_{\mathcal{U}}$

Relaxed:

Given $\epsilon > 0$, reconstruct $\tilde{u}_\epsilon \in \mathcal{U}$ with

$$|\lambda(\tilde{u}_\epsilon) - f(\lambda)| \leq \epsilon \text{ for all } \lambda \in \Lambda$$

and minimal norm $\|\tilde{u}_\epsilon\|_{\mathcal{U}}$

Quadratic Optimization

Minimize $\|\tilde{u}_\epsilon\|_{\mathcal{U}}^2$ in RKHS \mathcal{U} with kernel Φ
under linear constraints

$$-\epsilon \leq \lambda(\tilde{u}_\epsilon) - f(\lambda) \leq +\epsilon \text{ for all } \lambda \in \Lambda$$

Feasibility \Rightarrow Solvability

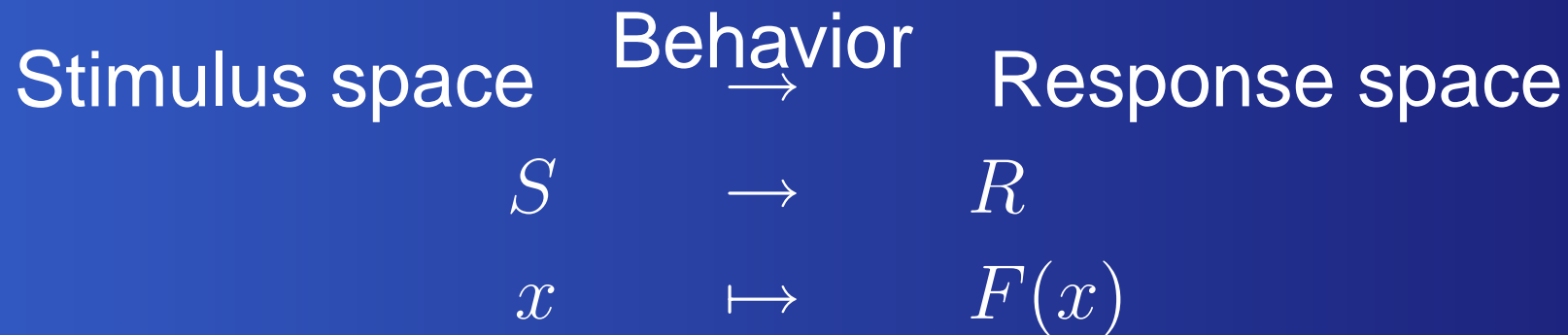
Solution is **only** based on functions $\lambda^x \Phi(x, \cdot)$
where $\lambda \in \Lambda$ satisfies

$$\lambda(\tilde{u}_\epsilon) - f(\lambda) = \pm\epsilon$$

active constraint, **support vector**

Problem: How many support vectors are needed?

Learning



Training:

Given meshless pairs $(x_j, z_j) \in S \times R$

find F with $F(x_j) = z_j$ (Interpolation)

Then: use F on unknown inputs x

Learning with Kernels

“Kernel trick” for $R = \mathbb{R}$

$K : S \rightarrow \mathcal{F}$ = “feature” space

Find optimal $G : \mathcal{F} \rightarrow \mathbb{R}$ with

$$z_j = G(\underbrace{K(x_j)}_{y_j}) =: F(x_j)$$

Interpolation in RKHS on \mathcal{F} with kernel Φ
Solution:

$$G(y) = \sum_j \alpha_j \Phi(y_j, y)$$

$$F(x) = G(K(x)) = \sum_j \alpha_j \Phi(K(x_j), K(x))$$

Optimized Learning with Kernels

Minimize $\|G\|_{\mathcal{U}}^2$ under constraints

$$-\epsilon \leq z_j - G(K(x_j)) \leq \epsilon$$

Feasibility \Rightarrow Solvability

Solution is **only** based on training samples x_j
where G satisfies

$$G(K(x_j)) - z_j = \pm\epsilon$$

active constraint, **support vector**

Example: Michael Schumacher

Example: Learning the peaks function of MATLAB

Example: Census data

Connection to Greedy Methods

$\Lambda_N = \{\lambda_1, \dots, \lambda_N\} \subset \Lambda \subset \mathcal{U}^*$, $f : \Lambda \rightarrow \mathbb{R}$, $\epsilon > 0$.

Assume $\tilde{u}_N \in \mathcal{U}$ is **minimum norm function** with

$$\lambda_j(\tilde{u}_N) = f(\lambda_j) \text{ for all } \lambda_j \in \Lambda_N.$$

Then find $\lambda \in \Lambda \setminus \Lambda_N$ such that

$$\epsilon_N := \max_{\lambda} |\lambda(\tilde{u}_N) - f(\lambda)|$$

If $\epsilon_N > \epsilon$ set $\lambda_{N+1} := \lambda$ and repeat.

Under weak assumptions: $\lim_{n \rightarrow \infty} \epsilon_N = 0$

Example: Greedy reconstruction of the peaks function

Open Problem

Within quadratic optimization:

Given $\Lambda \subset \mathcal{U}^*$, $f : \Lambda \rightarrow \mathbb{R}$, given $\epsilon > 0$

Determine $N(\epsilon)$ =number of support vectors

Part III

Preconditioning

Polynomials on Meshless Data

$$\begin{aligned} \mathbb{P}_m^d &:= d\text{-variate poly's of order } \leq m \\ &= \text{span } \{p_1, \dots, p_Q\}, \quad Q = \binom{m-1+d}{d} \end{aligned}$$

$$\Lambda := \{\lambda_1, \dots, \lambda_N\} \subset \mathcal{U}^*$$

$$P_m(\Lambda) := (\lambda_k(p_j))_{1 \leq j \leq Q, 1 \leq k \leq N}$$

$$\mu(\Lambda) := \max \{m : \text{rank } P_m(\Lambda) < N\}$$

$$\text{rank } P_{\mu(\Lambda)}(\Lambda) < N = \text{rank } P_{\mu(\Lambda)+1}(\Lambda)$$

Divided Differences

$$D_m(\Lambda) := \ker P_m(\Lambda) \subseteq \mathbb{R}^N$$

$$\alpha \in D_m \Leftrightarrow \sum_{k=1}^N \alpha_k \lambda_k(p) = 0 \text{ for all } p \in P_m^d$$

$$\mathbb{R}^N = D_0(\Lambda) \supseteq D_1(\Lambda) \supseteq \dots$$

$$\dots \supseteq D_{\mu(\lambda)}(\Lambda) \neq \{0\} = D_{\mu(\lambda)+1}(\Lambda)$$

Divided difference basis

$$\alpha^1, \dots, \alpha^N \in \mathbb{R}^N \text{ for } X$$

$$\alpha^j \in D_{t_j} \setminus D_{t_j+1}, \quad 0 = t_1 \leq \dots \leq t_N = \mu(\Lambda)$$

Divided Difference Matrix

$$A = \left(\alpha_k^j \right)_{1 \leq j, k \leq N}$$

with divided difference basis $\alpha^1, \dots, \alpha^N \in \mathbb{R}^N$
wrt. Λ

$$\sum_{k=1}^N \alpha_k^j \lambda_k(p) = 0 \text{ for all } p \in \mathbb{P}_{t_j}^d, \quad 1 \leq j \leq N$$

for polynomial orders $0 = t_1 \leq \dots \leq t_N = \mu(\Lambda)$

Depends on Λ , **not on any rbf**

Scaled analytic radial basis function

$$\phi_c(r) = f(c^2 r^2) = \sum_{\ell=0}^{\infty} f_{\ell} c^{2\ell} r^{2\ell}$$

Interpolation matrix:

$$C_c := \left(\lambda_k^x \lambda_j^y \phi(c^2 \|x - y\|_2) \right)_{1 \leq j, k \leq N}$$

Scaling matrix:

$$B_c := \left(c^{-t_j} \delta_{jk} \right)_{1 \leq j, k \leq N}$$

Preconditioning Transformation

$$\begin{aligned}
 & e_j^T \cdot B_c^T \cdot A \cdot C_c \cdot A \cdot B_c \cdot e_k \\
 = & \sum_{r=1}^j c^{-t_j} \alpha_r^j \sum_{s=1}^k c^{-t_k} \alpha_s^k \sum_{l=0}^{\infty} f_l c^{2l} \lambda_r^x \lambda_s^y \|x - y\|_2^{2l} \\
 = & \sum_{2l \geq t_j + t_k}^{\infty} f_l c^{2l - t_j - t_k} \underbrace{\sum_{r=1}^j \sum_{s=1}^k \alpha_r^j \alpha_s^k \lambda_r^x \lambda_s^y \|x - y\|_2^{2l}}_{\text{degree} \leq 2l - t_j - t_k} \\
 \rightarrow & f_{(t_j + t_k)/2} \sum_{r=1}^j \sum_{s=1}^k \alpha_r^j \alpha_s^k \lambda_r^x \lambda_s^y \|x - y\|_2^{t_j + t_k}
 \end{aligned}$$

for $t_j + t_k = 2l$ even

Limit Matrix

$$\lim_{c \rightarrow 0} B_c^T \cdot A \cdot C_c \cdot A \cdot B_c$$

converges to a matrix with entries

0

$t_j + t_k$ odd

$$f_{(t_j+t_k)/2} \sum_{r=1}^j \sum_{s=1}^k \alpha_r^j \alpha_s^k \lambda_r^x \lambda_s^y \|x - y\|_2^{t_j+t_k}$$

$t_j + t_k = 2\ell$ even

Example: Preconditioning

Least Interpolation

Using the polynomial basis

$$v_j(x) := \sum_{k=1}^N \alpha_k^j \lambda_k^y \|x - y\|_2^{2t_j}, \quad 1 \leq j \leq N$$

one can solve the generalized polynomial interpolation problem

$$\lambda_j(p) = \lambda_j(u), \quad 1 \leq j \leq N$$

and this interpolation uses the least possible degree $\mu(\Lambda)$.

Open Problems

- Use for real-world problems
- Localize

The End